

# Speaker Count Application for Smartphone Platforms

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**Abstract**—This paper presents a Speaker Count (SC) algorithm based on pitch estimation designed to recognize single-speaker audio recordings from two-speaker recordings. The paper reports the implementation for Symbian OS smartphones. The proposed solution is aimed at limiting implementation complexity and related battery consumption with respect to the schemes available in the literature. This action is mandatory due to the restricted resources available on smartphones. A practical experimental campaign of the proposal is conducted in real smartphones. The Speaker Count method has produced encouraging experimental results. The results also show that the implemented method allows saving energy and acting in a reasonable amount of time.

**Index Terms**— Multimedia Communications, Context Aware Applications, Audio Speaker Count, Low Computational Load, Low Battery Consumption.

## I. INTRODUCTION

INTERDISCIPLINARY advances are required to innovate in the field of pervasive computing and networking: new communication and networking solutions, new and less complex operating systems, miniaturized memorization capacity, efficient signal processing and context aware solutions. Context-aware applications are highly customizable services tailored to the user's preferences and needs and relying on the real-time knowledge of the user's surroundings, without requiring complex configuration on the user's part. In this view, smartphones can be considered versatile devices and offer a wide range of possible uses. Their technological evolution, combined with their increasing diffusion, gives mobile network providers the opportunity to come up with more advanced and innovative services. In order to provide context-aware services over smartphones, a description of mobile device environment must be obtained by acquiring and combining context data from different sources. Even if there are not yet available applications on smartphones, the number of active speakers in the surroundings can be useful context information. Determining the number of speakers participating in a conversation, which is the Speaker Count (SC) problem,

poses a greater challenge, on one hand, when no information about the speakers is available [1] and, on the other hand, if computational and energetic resources are limited as in the smartphones' case. Several speaker count algorithms have been designed, both for closed- and open-set applications. In the former case, speaker count implies the classification of data belonging to speakers whose identity is known, while in the open-set scenario there is no available *a priori* knowledge on the speakers.

Although in many cases promising results have been obtained for speaker count, available methods are not specifically designed for mobile devices and their computational requirements do not take into account the limited smartphone processing power and the time requirements of context-aware applications (e.g., [1]).

This paper presents a simple speaker count algorithm designed to recognize single-speaker (1S) recordings from two-speaker (2S) recordings operating in open-set scenarios.

The paper is organized as follows. A brief review of various speaker count methods proposed in the literature is provided in Section II. The proposed speaker count algorithm is described in Section III. Experimental results also in terms of recognition time, computational complexity, and battery consumption are presented in Section IV, which also includes audio recording database used for classifier training and testing. The conclusions are contained in Section V.

## II. RELATED WORK

Many of the existing speaker count methods are based on the calculation of spectral features, e.g. linear predictive cepstral coefficients [2], line spectral pairs, log-area ratio, mel-frequency cepstral coefficients [3], area coefficients, reflection coefficients [4]. The speaker count method presented in [5] employs a feature derived from the time-domain of the audio signal: the pitch estimation. Most algorithms use the classification of individual speech signal segments through classifiers such as Vector Quantizers [5], GMMs and Neural Tree Networks [4].

The percentages of correct recognition of the number of speakers obtained by the evaluated speaker count methods taken from the literature are shown in Table I.

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TABLE I  
CLASSIFICATION ACCURACIES (PERCENT) OBTAINED BY THE EVALUATED  
SPEAKER COUNT METHODS

Reference	Classes	Closed Set	Open Set
[2]	1S vs. more than 1S	-	92.5
	1S vs. 2S vs. more than 2S	-	77.5
	1S vs. 2S vs. 3S vs. 4S	-	63
[3]	1S vs. 2S	-	79.6
	1S vs. 2S vs. 3S	-	72.3
	1S vs. 2S vs. 3S vs. 4S	-	62.5
[5]	1S vs. 2S	83.5	64.4

However, all the above-mentioned methods are hardly applicable on smartphones. Their computational load is heavy. Algorithms that consider the limited processing power of smartphones and the time requirements of context-aware applications are strongly necessary.

### III. PROPOSED SPEAKER COUNT (SC) METHOD

#### A. Proposed Speaker Count Algorithm

The proposed speaker count method is designed to distinguish one-speaker audio recordings (1S) from two-speaker ones (2S). It is designed to operate in an open-set scenario and is based on audio recording pitch estimation.

The signal to be classified as one or two speaker is identified as  $s(n), n = 1, \dots, N$ . The SC method introduced in this paper is composed of the following steps.

- 1) The signal  $s(n)$  is divided into frames.
- 2) The pitch frequency for each frame is estimated.
- 3) A number of frames of  $s(n)$  is grouped into blocks.
- 4) The pitch PDF (Probability Density Function) is estimated for each block.
- 5) Features are extracted from each pitch PDF.
- 6) The decision about one or two speaker audio recording is taken for each block by a Gaussian Mixture Model (GMM) classifier on the base of the extracted pitch features. Once all blocks are classified, the whole audio recording is assigned to the class to which the majority of blocks have been assigned.

The main novelty of this paper stands in points 2, 4, and 5, as well as in the practical implementation of the designed SC method on smartphones available off the shelf.

#### B. Pitch Frequency Estimation

The fundamental frequency of a periodic signal is defined as the reciprocal of its period. For audio signals such as speech, which exhibit a relative periodicity, the fundamental frequency is also referred to as pitch.

Given the real-value discrete-time signal of length  $N$ ,  $s(n) n \in [0, N-1]$ , its autocorrelation is defined as

$$R(\tau) = \sum_{n=0}^{N-1-\tau} s(n)s(n+\tau) \quad \tau \in [0, 1, \dots, N-1] \quad (1)$$

Being in the case of audio speech signals, the set of possible

samples  $\tau$  of the autocorrelation function can be reduced. [6] reports that the pitch of a speech signal, due to physiological reasons, is contained in a limited range  $[P_1, P_2]$  with  $P_1 = 50$  Hz and  $P_2 = 500$  Hz. It limits the  $\tau$  range between the two following values:

$$\tau_1 = \left\lfloor \frac{F_s}{P_2} \right\rfloor \quad \text{and} \quad \tau_2 = \left\lfloor \frac{F_s}{P_1} \right\rfloor \quad (2)$$

where  $F_s$  is the sampling frequency applied to the original analog signal to obtain the discrete-time signal  $s(n)$ . In practice, the applied autocorrelation definition is:

$$\hat{R}(\tau) = \sum_{n=0}^{N-1-\tau} s(n)s(n+\tau) \quad (3)$$

$$\tau \in \left[ \left\lfloor \frac{F_s}{P_2} \right\rfloor, \left\lfloor \frac{F_s}{P_2} \right\rfloor + 1, \left\lfloor \frac{F_s}{P_2} \right\rfloor + 2, \dots, \left\lfloor \frac{F_s}{P_1} \right\rfloor \right]$$

From the computational viewpoint, the physiological limitation of the pitch range implies a first significant reduction of the number of samples involved in the computation and, as a consequence, of the overall complexity. Pitch is linked to signal periodicity. The autocorrelation shows how well the signal correlates with itself at a range of different delays. So, given a ‘‘sufficiently periodical’’ speech recording, its autocorrelation will present its highest value at delays corresponding to multiples of pitch periods [6].

Being the pitch period defined as in (4),

$$\tau_{pitch} = \arg \max_{\tau} \hat{R}(\tau) \quad (4)$$

the pitch is defined as

$$\rho_{pitch} = \frac{F_s}{\tau_{pitch}} \quad (5)$$

To further reduce the computational complexity of the pitch estimation method, a downsampled version of the autocorrelation function is introduced in this paper by using a downsampling factor  $r$ . Being  $N$  the cardinality of the original set of autocorrelation samples the downsampled version uses  $K = rN$  samples. In practice the downsampled autocorrelation is defined as:

$$\tilde{R}(\tau) = \sum_{n=0}^{N-1-\tau} x(n)x(n+\tau) \quad (6)$$

$$\tau \in \left[ \left\lfloor \frac{F_s}{P_2} \right\rfloor, \left\lfloor \frac{F_s}{P_2} \right\rfloor + \frac{1}{r}, \left\lfloor \frac{F_s}{P_2} \right\rfloor + \frac{2}{r}, \dots, \left\lfloor \frac{F_s}{P_1} \right\rfloor \right]$$

It means that  $\tilde{R}(\tau)$  considers just one sample of  $\hat{R}(\tau)$  out of  $\frac{1}{r}$  in the interval  $\left[ \left\lfloor \frac{F_s}{P_2} \right\rfloor, \left\lfloor \frac{F_s}{P_1} \right\rfloor \right]$ . In consequence,

$\tilde{\tau}_{pitch} = \arg \max_{\tau} \tilde{R}(\tau)$  and  $\tilde{\rho}_{pitch} = \frac{F_s}{\tilde{\tau}_{pitch}}$ . In order to still

correctly determine the maximum of the full autocorrelation, thus preventing errors in pitch estimation, a maximum ‘‘Fine Search’’ method has been designed and implemented in this

paper to partially compensate the inaccuracies introduced by downsampling. Starting from the delay corresponding to the pitch obtained by the downsampled autocorrelation function  $\tilde{\tau}_{pitch}$ , the values of  $\hat{R}(\tau)$ , in (3), are computed for  $\tau$  values adjacent to  $\tilde{\tau}_{pitch}$  up to a depth of  $\pm \left\lfloor \frac{1}{r} - 1 \right\rfloor$ . Their maximum is taken as new pitch period  $\tau'_{pitch}$ . Analytically:

$$\tau'_{pitch} = \arg \max_{\tau} \hat{R}(\tau), \tau \in \left[ \tilde{\tau}_{pitch} - \frac{1}{r} + 1, \dots, \tilde{\tau}_{pitch} + \frac{1}{r} - 1 \right] \quad (7)$$

$$\rho'_{pitch} = \frac{F_s}{\tau'_{pitch}} \quad (8)$$

$\rho'_{pitch}$  is the reference pitch value for the remainder of this paper.

### C. PDF Estimation

$s(n)$ ,  $n=1, \dots, N$  is first divided into  $F = \left\lfloor \frac{N}{L} \right\rfloor$  abutted

$L$ -sample frames. A pitch estimate is computed for each frame by applying the described method. Sets of  $D$  consecutive frames are grouped together in blocks, in order to allow the computation of a pitch PDF for each block.

Consecutive blocks are overlapped by  $V$  frames (i.e., the last  $V$  frames of a block are the first  $V$  of the following one) in order to take into account the possibility of a signal portion representing fully voiced speech falling across consecutive, non-overlapping blocks, and therefore its contributions to the classification process being divided between the two blocks.

This means there are a total of  $B = \left\lfloor \frac{(F-V)}{(D-V)} \right\rfloor$  blocks. The  $t$ -th block is defined as  $b_t$ . For each block  $b_t$  there are  $V$  pitch values computed as in (8) identified as  $\rho_{pitch}^{b_t, v}$ ,  $v=1, \dots, V$ . The PDF for block  $b_t$  spans a frequency interval ranging from the minimum to the maximum computed pitch value. Such frequency interval is divided into  $H$  smaller frequency bins of size  $\Delta p$  Hz that is determined through extensive tests.  $p$  is the variable identifying the frequency.

The PDF for each block  $b_t$  is estimated by a weighted count of the number of occurrences of single  $\rho_{pitch}^{b_t, v}$ ,  $v=1, \dots, V$  within each frequency bin  $h=0, \dots, H-1$ .

In short:

$$PDF(p) = \sum_{h=0}^{H-1} w_h \cdot \text{rect} \left( \frac{p - \left[ \left( \frac{1}{2} + h \right) \Delta p \right]}{\Delta p} \right) \quad (9)$$

$w_h$  is the coefficient associated to the  $h$ -th bin and implements the mentioned weighted count, as explained in the following. If  $w_h$  is the number of  $\rho_{pitch}^{b_t, v}$ ,  $v=1, \dots, V$ , whose values fall within the  $h$ -th bin, then the PDF is simply computed through the number of occurrences and is called "histogram count".

In order to have a more distinct PDF and, consequently, more accurate features vectors, this paper links the coefficient  $w_h$  to the energy distribution of the signal  $s(n)$  in the frequency range where the PDF of a block is spanned. Given the Discrete Time Fourier Transform (DTFT) of the signal  $s(n)$ ,

$$DTFT(s(n)) = S(f) = \sum_{n=0}^{N-1} s(n) \cdot e^{-j2\pi n f}, \quad f \in [P_1, P_2],$$

with  $P_1 = 50\text{Hz}$  and  $P_2 = 500\text{Hz}$ , as defined in the previous subsection; given the definition of signal energy and the

Parseval relation,  $E_s = \sum_{n=0}^{N-1} |s(n)|^2 = \int_{-\frac{1}{2}}^{+\frac{1}{2}} |S(f)|^2 df$ , the energy

component at a given frequency is  $|S(f)|^2$ . To evaluate the energy component of each frequency bin  $h$ , we would need to know the energy contribution carried by each pitch occurring within bin  $h$ . In practice, we would need  $|S(\rho_{pitch}^{b_t, v})|^2$ ,  $\forall v=1, \dots, V$ .

But  $S(f)$  is a continuous function. It must be substituted by its sampled version, the Digital Fourier Transform (DFT) to be practically computed and used. The DFT of signal  $s(n)$

is defined as  $DFT(s(n)) = S(k) = \sum_{n=0}^{N-1} s(n) \cdot e^{-j2\pi n \frac{k}{N}}$ ,

$\forall k \in 0, \dots, N-1$ . The problem is that the DFT is a function of an integer number  $k$  while  $\rho_{pitch}^{b_t, v} \in \mathbb{R}$ . So, to allow the computation,  $\rho_{pitch}^{b_t, v}$  is approximated in this paper with the closest integer number  $\rho_{pitch, \text{int}}^{b_t, v}$  defined as follows:

$$\rho_{pitch, \text{int}}^{b_t, v} = \begin{cases} \left\lfloor \rho_{pitch}^{b_t, v} \right\rfloor, & \text{if } \rho_{pitch}^{b_t, v} - \left\lfloor \rho_{pitch}^{b_t, v} \right\rfloor \leq \frac{1}{2} \\ \left\lceil \rho_{pitch}^{b_t, v} \right\rceil, & \text{if } \rho_{pitch}^{b_t, v} - \left\lfloor \rho_{pitch}^{b_t, v} \right\rfloor > \frac{1}{2} \end{cases} \quad (10)$$

The coefficient  $w_h$  is defined as

$$w_h = \frac{\sum_{\substack{v \\ \rho_{pitch, \text{int}}^{b_t, v} \in \text{bin } h}} |S(\rho_{pitch, \text{int}}^{b_t, v})|^2}{\sum_{h=0}^{H-1} \sum_{\substack{v \\ \rho_{pitch, \text{int}}^{b_t, v} \in \text{bin } h}} |S(\rho_{pitch, \text{int}}^{b_t, v})|^2} \quad (11)$$

This assignment of  $w_h$  is used in the remainder of the paper. This idea leads to more distinct PDFs and more accurate features vectors, thus significantly improving the SC method performance compared to computing PDFs by simply executing a "histogram count".

### D. Features Definition

In order to determine the best feature vector  $\Omega$  that maximizes the efficiency of the proposed SC method, different feature vectors may be evaluated by combining different individual features representing the block PDF

dispersion. The evaluated features are the PDF maximum given by (12), the PDF mean computed according to (13), where  $p_h^c$  is the central frequency of the  $h$ -th bin, the PDF standard deviation defined in (14) and the absolute value, reported in (15), of the difference between the PDF mean and the central frequency of the bin containing the PDF maximum.

$$PDF_{\max} = \max_h w_h \quad h = 0, \dots, H-1 \quad (12)$$

$$PDF_{\text{mean}} = \sum_{h=0}^{H-1} p_h^c w_h \quad (13)$$

$$PDF_{\text{St.Dev.}} = \sqrt{\sum_{h=0}^{H-1} (p_h^c - PDF_{\text{mean}})^2 \cdot w_h} \quad (14)$$

$$PDF_{\text{disp}} = \left| PDF_{\text{mean}} - p_{h_{\max}}^c \right| \quad (15)$$

$$h_{\max} = \arg \max_h w_h$$

$\Omega$  may be composed by using, for example, subsets of the features mentioned above as tested in the performance evaluation section.

#### E. Gaussian Mixture Model Classification

Feature vector  $\Omega$  is employed to classify a block as either 1S or 2S, which are the considered speaker classes, through the Gaussian Mixture Model (GMM) classifier known in the literature. Once all individual blocks have been classified, the whole audio recording is classified through a ‘‘majority vote’’ decision: the chosen class is the one to which most blocks have been assigned.

### IV. PERFORMANCE INVESTIGATION

#### A. Audio Recording Database

Training and testing of the classifiers are carried out using a database of audio recordings acquired with a smartphone audio-recording application. The overall dataset is composed of audio recordings referred to five different situations: 1 Male speaker (1M), 1 Female speaker (1F), 2 Male speakers (2M), 2 Female speakers (2F) and 2 mixed speakers (2MF). The database is acquired using a 22 KHz sampling frequency and 16 bits per sample, and all recordings are 4.5 s long. All audio recordings refer to different speakers in order to evaluate the classifier performances using data deriving from speakers that have not influenced classifier training (open-set application). A total of 50 recordings is acquired, 10 for each situation. The starting section of each recording is deleted in order to remove spurious signal peaks due to the turning-on phase of the smartphone microphone. As a consequence, not all recordings have the same amount of samples.

For the SC classifier, half of the recordings for each of the five situations is used for GMM training, the other half for testing.

#### B. Parameters Setting

During the experiments, the frame size  $L$  is set to 2048 samples. The block size  $D$  is set to 20 frames. The number of blocks for each recording varies between 3 and 4 due to the different length in terms of amount of samples. The overall dataset is composed of 194 blocks. The block overlap  $V$  is set to 10 frames, a trade-off between having many, heavily-overlapped blocks (which implies consecutive blocks bearing redundant information and added computational load) and few, slightly-overlapped blocks with the risk of having signal sections representing fully voiced speech fall across consecutive blocks.

Pitch values in the range 50 Hz - 500 Hz are considered as suggested in [6] and individual bins  $h$  represent intervals of approximately 10 Hz.

Starting from the computed PDF, feature vectors are computed as detailed previously. PDFs and feature vectors depend on the pitch estimation method and, as a consequence, are influenced by its tuning. The downsampled autocorrelation function in (6) is employed in this paper. The downsampling may impact the precision of the overall method and therefore its performance. To define the best trade-off between precision and computational load, several tests have been carried out by comparing the features obtained through the full autocorrelation function and through the downsampled one.

Downsampling factors  $r = \frac{1}{2}, \frac{1}{3}, \frac{1}{4}, \frac{1}{5}, \frac{1}{6}, \frac{1}{7}$  have been tested. Related figures are not reported for the sake of synthesis;  $r = \frac{1}{5}$  represents the best compromise and it is the downsampling factor used in the tests whose results are discussed in the following.

#### C. Speaker Count Results

Different feature vectors have been evaluated to select the most discriminating one. The required classification is between 1 Speaker (1S) or 2 Speakers (2S). After a deep analysis, the feature vector ultimately used for GMM classification is  $\Omega = \{PDF_{\max}, PDF_{\text{St.Dev.}}\}$ , which not only leads to the best block classification performance but also requires the computation of only two features, thus reducing the computational load.

Table II reports the percentage of correct classification for 1S and 2S by using the whole dataset.

TABLE II  
CORRECT CLASSIFICATION PERCENTAGE OF WHOLE TEST RECORDING FOR 1 AND 2 SPEAKERS ( $\Omega = \{PDF_{\max}, PDF_{\text{St.Dev.}}\}$ )

		Predicted	
		1S	2S
Actual	1S	60%	40%
	2S	40%	60%

Correct Classification (average): 60%

The obtained percentages are not so far from the results for the same 1S vs 2S case through the other available open-set algorithms reported in Table I, but the speaker count classifier based on the feature vectors previously described leads to results that do not live up to our expectations. Most of classification errors happened in the cases 2M and 2F that can be misclassified as 1M and 1F respectively. The motivation is that same-gender speakers could have pitch estimates close enough in value to lead to 2S PDFs similar to 1S PDFs of the same gender. This observation has brought to the design of a new GMM SC classifier, in order to distinguish not two classes (1S and 2S) but three gender-based classes: 1M, 1F and 2MF. The scheme is called SC classifier 1F-1M-2MF to avoid confusion with the 1S-2S case. The case 2M and 2F, which is still a problem, is not considered for now and its investigation is left to further research. Again, different feature vectors are evaluated. The best performance has been provided by 2-dimensional feature vectors  $\Omega = \{PDF_{mean}, PDF_{disp}\}$  and  $\Omega = \{PDF_{mean}, PDF_{max}\}$ .

Anyway, independently of the feature vector, the only classification errors involve exclusively class 2MF, i.e. test recording blocks belonging to classes 1M and 1F have never been mistaken one for another.

The feature vector ultimately used for GMM classification is  $\Omega = \{PDF_{mean}, PDF_{max}\}$ , since it leads to the best test set classification and, unlike  $\Omega = \{PDF_{mean}, PDF_{dispersion}\}$ , classifies 1F and 1M test recordings with comparable accuracies. Table III contains the classification results by using the test recordings of the whole dataset. Table IV displays the classification results shown in Table III mapped to the two-class (1S and 2S) SC, for a better comparison with the results shown in Table II. As can be seen, the new 1F-1M-2MF scheme does indeed lead to better performance.

This SC scheme performance is comparable (and, in one case, better) with the other methods in the literature (Table I) for similar sets of classes. It is important to remind that the methods in Table I are hardly implementable on smartphones because they imply a number of operations incompatible with the computation capacity of a smartphone.

Concerning the use of the full autocorrelation instead of the downsampled one, it does not provide clear performance benefit, as better focused in the next sub-section.

TABLE III  
CORRECT CLASSIFICATION PERCENTAGE OF WHOLE TEST RECORDING FOR 1F, 1M, AND 2MF ( $\Omega = \{PDF_{mean}, PDF_{max}\}$ )

		Predicted		
		1F	1M	2MF
Actual	1F	40%	0%	60%
	1M	0%	80%	20%
	2MF	20%	0%	80%

Correct Classification (average): 67%

TABLE V  
CORRECT CLASSIFICATION PERCENTAGE OF WHOLE TEST RECORDING FOR 1F, 1M, AND 2MF ( $\Omega = \{PDF_{mean}, PDF_{max}\}$ ) MAPPED ON 1S-2S SC

		Predicted	
		1S	2S
Actual	1S	60%	40%
	2S	20%	80%

Correct Classification (average): 70%

#### D. Computational Time and Energy Consumption Analysis

A Symbian OS application implementing the SC algorithm has been designed as part of this study.

The smartphone used for all the experiments is a Nokia N95 with Symbian S60 3<sup>rd</sup> Edition, Feature Pack 1 operating system. This kind of mobile phone is popular because of its usability and its interesting features. Its most important technical parameters are:

- Battery: Nokia (BL-5F) 950 mAh, 3.7 V;
- Dynamic Memory: 160 MB;
- Processor: RM-159 TI OMAP 2420 ARM-11 330 MHz.

Experiments have been carried out in order to evaluate the performance of the proposed SC approach also in terms of computational load and energy consumption. The chosen metrics are the Recognition Time (RT) in s and the Residual Battery Lifetime (RBL) in hours. The SC algorithm has been compared to another version that does not implement autocorrelation downsampling to emphasize the advantages of the design choices proposed in this work. The two options are identified as:

- Version 1, where the autocorrelation function is downsampled and the pitch is computed through equations (6) and (7) with  $r = \frac{1}{5}$ . It is the proposed SC approach.
- Version 2, where the autocorrelation function is not downsampled and is computed as in equation (3).

Figure 1 shows the overall Recognition Time RT (in seconds) for the SC scheme as well as its main components: the time required to compute the pitch, the DFT, and the other operations to complete the algorithm. It has been separated into the three contributions for the sake of clearness and to allow a deeper investigation and possible further improvements. The overall value is the average of the values obtained from a set of 15 runs of the algorithm. It is worth noting that an overall RT of 2.73 s, measured on real smartphones, is compliant with most current context-aware applications.

Computing a non-downsampled autocorrelation as in Version 2 increases the pitch computation time to 5.79 s and the overall RT to 7.28 s, 266.67% more of Version 1. On the other hand, from the recognition percentage viewpoint

Version 2 does not give a meaningful advantage with respect to Version 1. It is slightly above the 70% measured for Version 1. Nevertheless, the significant advantage in terms of both RT and RBL (detailed in the following) justifies a few less correct recognition percentage points.

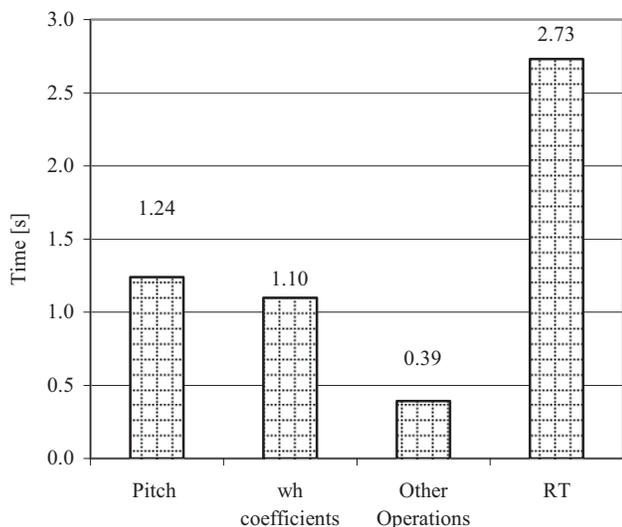


Fig. 1. Recognition Time results for the SC Algorithm.

As previously introduced, the SC algorithm versions were also tested under an energetic point of view using the Nokia Energy Profiler (NEP). NEP is a tool, provided by Nokia, which allows monitoring some of the most important energetic parameters such as power and current consumption, CPU load and Residual Battery Lifetime (RBL).

In these terms the SC algorithm was tested with 15 recordings and, for each audio file, the RBL was measured using the NEP tool. Again the proposed scheme was compared with non-downsampled autocorrelation Version 2. Each version of the algorithm is run and monitored on a 30 s window. The average values of the aforementioned RBL are measured in the monitoring window and can be seen in Fig. 2.

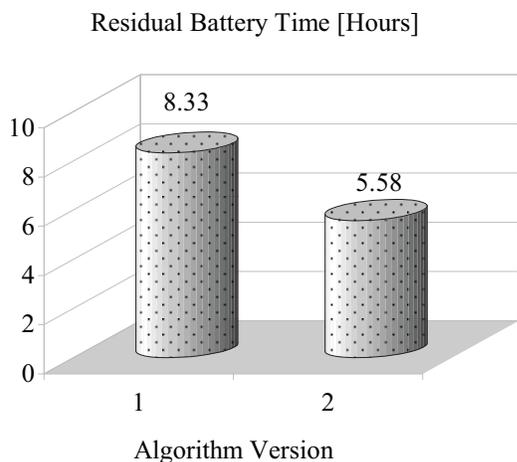


Fig. 2. Residual Battery Lifetime of each SC algorithm: Version 1 and 2.

In the conditions previously introduced, the proposed SC algorithm, running in a 30 s windows, allows a Residual Battery Lifetime of 8.33 hours. This is a very satisfactory result. Version 2 guarantees a RBL below 6 hours. In short: the SC scheme guarantees a good recognition percentage, performs the action in a reasonable amount of time (about 2.7 s), and saves a significant amount of RBL.

Such considerations have been also confirmed by the measure of the CPU usage, shown in percentage in Fig. 3, required by the algorithm introduced in this paper and carried out by the NEP. Again Fig. 3 compares Versions 1 and 2.

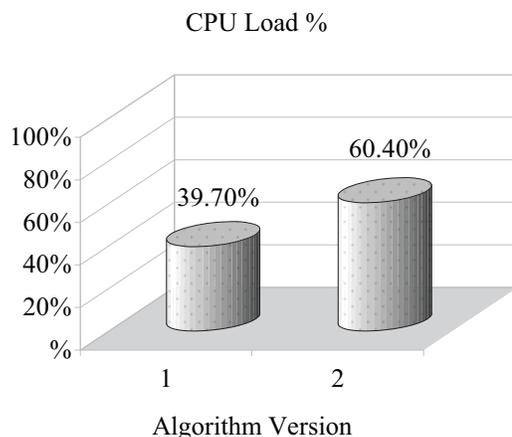


Fig. 3. Employed CPU Percentage of each SC algorithm version.

## V. CONCLUSIONS

Experiments carried out with the proposed speaker count method lead to the correct classification of 60% of the test recordings. More encouraging results (70% of test recordings classified correctly) are obtained by adding knowledge of the speaker gender, object of future research. The proposed method has been implemented as a Symbian OS smartphone application.

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